Video Scene Change Detection v1.0

LogiCORE IP Product Guide

Vivado Design Suite

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Chapter 1

Introduction

The Xilinx[®] Video Scene Change Detection IP provides a video processing block that implements the scene change detection algorithm. The IP core calculates a histogram on a vertically subsampled luma frame for consecutive frames. The histograms of these frames are then compared using the sum of absolute differences (SAD). This IP core is programmable through a comprehensive register interface to control the frame size, video format, and subsampling value.

Features

- Input streams can be read from memory mapped AXI4 interface or from AXI4-Stream interface.
- Supports up to eight streams in the memory mapped mode and one stream in the stream mode.
- Supports Y8 and Y10 formats for memory interface.
- Supports RGB, YUV 444, YUV 422, and YUV 420 formats for stream interface.
- Supports 8, 10, 12, and 16 bits per color component input and output on AXI4-Stream interface.
- Supports one, two, or four pixel width for stream mode and one pixel width for memory mode.
- Supports spatial resolutions ranging from 64 × 64 up to 8,192 × 4,320.
- Supports 4k 60 fps in all supported device families.
- Supports 32-bit and 64-bit DDR memory address access.



IP Facts

LogiCORE™ IP Facts Table						
	Core Specifics					
Supported Device Family ¹	UltraScale+™ Families, UltraScale™ Architecture, Zynq®-7000 SoC, 7 series					
Supported User Interfaces	AXI4-Master, AXI4-Lite, AXI4-Stream ²					
Resources	Performance and Resource Use web page					
	Provided with Core					
Design Files	Not Provided					
Example Design	Yes					
Test Bench	Not Provided					
Constraints File	Xilinx Design Constraints (XDC)					
Simulation Model	Encrypted RTL					
Supported S/W Driver ³	Standalone, Linux V4L2					
	Tested Design Flows ⁴					
Design Entry	Vivado® Design Suite					
Simulation	For supported simulators, see the Xilinx Design Tools: Release Notes Guide.					
Synthesis	Vivado Synthesis					
Support						
Release Notes and Known Issues	Master Answer Record: 70293					
All Vivado IP Change Logs Master Vivado IP Change Logs: 72775						
Provided by 2	Xilinx® at the Xilinx Support web page					

Notes:

- 1. For a complete list of supported devices, see the Vivado[®] IP catalog.
- 2. Video protocol as defined in the "Video IP: AXI Feature Adoption" section of *Vivado Design Suite: AXI Reference Guide* (UG1037).
- 3. Standalone driver details can be found in the Vitis directory (<install_directory>/Vitis/<release>/data/ embeddedsw/doc/xilinx_drivers.htm). Linux OS and driver support information is available from the Xilinx Wiki page.
- 4. For the supported versions of the tools, see the Xilinx Design Tools: Release Notes Guide.
- 5. Resource utilization is available at Performance and Resource Use web page web page.



Chapter 2

Overview

The Xilinx[®] Video Scene Change Detection core detects scene change between two consecutive video frames received on either memory interface or stream interface. Memory or stream mode can be selected from the IP GUI.

Feature Summary

The Video Scene Change Detection IP is a configurable IP core that can read up to eight video streams in the memory mode and one video stream in the stream mode. In the memory mode, input is read from the memory mapped AXI4 interface. In the stream mode, input is read from the AXI4-Stream interface and the output stream is same as the received input stream.

The Video Scene Change Detection IP supports resolutions ranging from 64 × 64 to 8,192 × 4,320 with up to three color components, each of 8, 10, 12, and 16 bits. The Video Scene Change Detection IP sends the interrupt signals after generating the SAD values for all the input streams of every frame. In case of the memory mode, the SAD values are calculated for each input stream one after the other sequentially and the interrupt is generated after the SAD calculation of final stream. On interrupt generation, the SAD values are read from the SAD registers for configured number of streams to compare them with a user decided threshold value to determine if a scene change has occurred. In the memory mode, you can dynamically configure the buffer addresses from where the input video stream is read.

Applications

The Video Scene Change Detection core is used for the following purposes:

- Video surveillance
- Video streaming
- Video conferencing



One of the applications of the Video Scene Change Detection IP is that it can be used with the Zynq UltraScale+[™] VCU subsystem. It helps the VCU subsystem to identify when to update the reference frame for better performance while encoding streams. This is done using the Video Scene Change Detection IP interrupt flag. It sends fewer frames that help in reducing the compressed stream size, thereby saving bandwidth.

In the VCU subsystem, the encoder rate control logic works based on the previous history and statistics gathered during the encoding session. When a scene change happens, the complexity of the frame changes and previously calculated statistics may not hold good. The rate control logic takes longer to adjust to the new content. If the source provides the scene change detection flag along with the input buffer encoder, the rate control logic can quickly adjust its statistics and prevent overshoot/undershoot in the bitrate. This results in updating the reference frame for better performance.

Licensing and Ordering

This Xilinx[®] LogiCORE[™] IP module is provided at no additional cost with the Xilinx Vivado[®] Design Suite under the terms of the Xilinx End User License.

Note: To verify that you need a license, check the License column of the IP Catalog. Included means that a license is included with the Vivado[®] Design Suite; Purchase means that you have to purchase a license to use the core.

For more information about this core, visit the Video Scene Change Detection product web page.

Information about other Xilinx[®] LogiCORE[™] IP modules is available at the Xilinx Intellectual Property page. For information about pricing and availability of other Xilinx[®] LogiCORE IP modules and tools, contact your local Xilinx sales representative.





Chapter 3

Product Specification

Standards

The Video Scene Change Detection IP is compliant with the AXI4-Stream Video Protocol, AXI4-Lite interconnect, and memory mapped AXI4 interface standards. For additional information, see the Video IP: AXI Feature Adoption section of the *Vivado Design Suite*: AXI Reference Guide (UG1037).

Performance

Maximum Frequencies

The following are typical clock frequencies for the target devices:

- UltraScale+[™] devices with -1 speed grade or higher: 300 MHz
- Virtex[®]-7 and Virtex[®] UltraScale[™] devices with -2 speed grade or higher: 300 MHz
- Kintex[®]-7 and Kintex[®] UltraScale[™] devices with -2 speed grade or higher: 300 MHz
- Artix[®]-7 devices with -2 speed grade or higher: 150 MHz

The maximum achievable clock frequency can vary. The maximum achievable clock frequency and all resource counts can be affected by other tool options, additional logic in the device, using a different version of Xilinx[®] tools, and other factors.

Throughput

The Video Scene Change Detection IP supports bi-directional data throttling between its AXI4-Stream slave and master intefaces. If the slave side data source is not providing valid data samples (s_axis_video_tvalid is not asserted), the core cannot produce valid output samples after its internal buffers are depleted. Similarly, if the master side interface is not ready to accept valid data samples (m_axis_video_tready is not asserted) the core cannot accept valid input samples after its buffers are full.



Latency

The following examples explain the latency requirements for the Video Scene Change Detection IP in both stream and memory based modes:

- Stream mode: In the stream mode, 4K video subsampled at a subsampling factor of 16 results in 3840*2160/16 = 518, 400 samples. If the IP processes 1 sample per clock at 100 MHz, it takes 518K/100M = 5.2 ms to pass all samples through the IP. The IP would consume 518, 400 bytes to complete this task. In this mode, the data passes from input to output. The IP needs to handle complete 4K data when configured to a maximum resolution of 4K. The IP need to run at 2 samples per clock at 300 MHz. There is no bandwidth requirement in the stream mode.
- **Memory mode:** In the memory mode, the IP does not need more than 4K/16 performance for subsampling at 16. You can cover that with 1 pixel per clock. In this mode, processing 4K video requires a peak bandwidth of 1000/5.2 * 518K = ~100 MB/s. Running the IP slower consumes less bandwidth. The latency is still 5.2 ms to get the SAD value in the output though you do not get any output samples.

Resource Utilization

For full details about performance and resource use, visit the Performance and Resource Use web page.

Port Descriptions

The Video Scene Change Detection IP uses industry standard control and data interfaces to connect to other system components. The following sections describe the various interfaces available within the core. The following figure illustrates the Video Scene Change Detection IP I/O diagram in memory mode. In this configuration, the IP has two AXI interfaces:

- AXI4-Lite control interface (s_axi_CTRL)
- Memory mapped AXI4 interface (m_axi_mm_video)





Figure 1: Scene Change Detection IP I/O Diagram Memory Mode



The following figure illustrates the Video Scene Change Detection IP I/O diagram for stream based mode. In this configuration, the IP has three AXI interfaces:

- AXI4-Lite control interface (s_axi_CTRL)
- AXI4-Stream streaming video input (s_axis_video)
- AXI4-Stream streaming video output (m_axis_video)

Figure 2: Scene Change Detection IP I/O Diagram Stream Mode



Common Interface Signals

The following table summarizes the signals which are either shared by or not part of the dedicated AXI4-Stream, memory mapped AXI4 data, or AXI4-Lite control interfaces.

Table 1: Common Interface Signals

Signal Name	I/O	Width	Description	
ap_clk	Ι	1	Video core clock	
ap_rst_n	Ι	1	Video core active-Low clock enable	
interrupt	0	1	Interrupt Request Pin	

The ap_clk and ap_rst_n signals are shared between the core, memory mapped AXI4 data interfaces, and the AXI4-Lite control interface.



- **ap_clk:** The memory mapped AXI4 and AXI4-Lite interfaces must be synchronous to the core clock signal ap_clk. All memory mapped AXI4 interface input signals and AXI4-Lite control interface input signals are sampled on the rising edge of ap_clk.
- **ap_rst_n:** The ap_rst_n pin is an active-Low, synchronous reset input pertaining to both AXI4-Lite and memory mapped AXI4 interfaces. When ap_rst_n is set to 0, the core resets at the next rising edge of ap_clk.
- **interrupt:** The interrupt status output bus can be integrated with an external interrupt controller that has independent interrupt enable/mask, interrupt clear, and interrupt status registers that allow interrupt aggregation to the system processor.

AXI4-Stream Video Interface

The Video Scene Change Detection IP has AXI4-Stream video input and output interfaces named s_axis_video and m_axis_video respectively, when the stream mode is enabled.

Both video streaming interfaces follow the interface specification as defined in the Video IP chapter of the *Vivado Design Suite: AXI Reference Guide* (UG1037). The video AXI4-Stream interface can be single, dual, or quad pixels per clock and can support 8, 10, 12, or 16 bits per component. The streaming interface configuration (samples per clock and bits per component) is chosen at the IP level and applies to all instances of the AXI4-Stream interface.

The following tables explain the pixel mapping of an AXI4-Stream interface with two pixels per clock and 10 bits per component configuration for all supported video color formats:

Table 2: Dual Pixels Per Clock, 10 Bits Per Component Mapping for RGB

69:60	59:50	49:40	39:30	29:20	19:10	9:0
Zero padding	R1	B1	G1	R0	В0	G0

Table 3: Dual Pixels Per Clock, 10 Bits Per Component Mapping for YUV 4:4:4

69:60	59:50	49:40	39:30	29:20	19:10	9:0
Zero padding	V1	U1	Y1	V0	U0	Y0

Table 4: Dual Pixels Per Clock, 10 Bits Per Component Mapping for YUV 4:2:2

69:60	59:50	49:40	39:30	29:20	19:10	9:0
Zero padding	Zero padding	Zero padding	V0	Y1	U0	Y0

The following table shows the interface signals for input and output AXI4-Stream video streaming interfaces.



Signal Name	I/O	Width	Description
s_axis_tdata	Ι	floor(((3× bits_per_component× pixels_per_clock) + 7) / 8) × 8	Input Data
s_axis_tready	0	1	Input Ready
s_axis_tvalid	0	1	Input Valid
s_axis_tdest	I	1	Input Data Routing Identifier
s_axis_tkeep	I	(s_axis_video_tdata width) / 8	Input byte qualifier that indicates whether the content of the associated byte of TDATA is processed as part of the data stream.
s_axis_tlast	I	1	Input End of Line
s_axis_tstrb	I	(s_axis_video_tdata width) / 8	Input byte qualifier that indicates whether the content of the associated byte of TDATA is processed as a data byte or a position byte.
s_axis_tuser	I	1	Input Start of Frame
m_axis_tdata	0	floor(((3 × bits_per_component× pixels_per_clock) + 7) / 8) × 8	Output Data
m_axis_tdest	0	1	Output Data Routing Identifier
m_axis_tid	0	1	Output Data Stream Identifier
m_axis_tkeep	0	(m_axis_video_tdata width) / 8	Output byte qualifier that indicates whether the content of the associated byte of TDATA is processed as part of the data stream.
m_axis_tlast	0	1	Output End of Line
m_axis_tready	I	1	Output Ready
m_axis_tstrb	0	(m_axis_video_tdata width) / 8	Output byte qualifier that indicates whether the content of the associated byte of TDATA is processed as a data byte or a position byte.
m_axis_tuser	0	1	Output Start of Frame
m_axis_tvalid	0	1	Output Valid

Table 5: AXI4-Stream Interface Signals

Notes:

All video streaming interfaces run at the IP core clock speed, ap_clk. 1.

For default values required to drive the AXI4-Stream interface signals that are not present in upstream or 2. downstream connected IPs, see the IP Using AXI4-Stream Video Protocol section of Vivado Design Suite: AXI Reference *Guide* (UG1037).

Memory Mapped AXI4 Interface

There is a memory mapped AXI4 interface named $m_axi_mm_video$. The memory mapped AXI4 interface runs on the ap_clk clock domain. The signals follow the specification as defined in the Vivado Design Suite: AXI Reference Guide (UG1037). The following table shows the pixel formats in the memory supported by the Video Scene Change Detection IP.



Table 6: Memory Mode Pixel Formats

Video Format	Description Bits Per Component		Bytes Per Pixel
Y8	Packed luma only	8	1 byte per pixel
Y10	Packed luma only	10	4 bytes per 3 pixel

The following sections explain the expected pixel mappings in memory for each of the listed formats.

Y8 Format

Packed luma-only eight bits per component. Every luma-only pixel in the memory is represented with 8 bits. The images need to be stored in the memory in raster order, that is, top-left pixel first, bottom-right pixel last. Y8 is presented as YUV 4:4:4 on the AXI4-Stream interface.

Table 7: Y8 Format

7:0	
Y	

Y10 Format

Packed luma-only 10 bits per component. Every three luma-only pixels in the memory is represented with 32 bits. The images need be stored in the memory in raster order, that is, top-left pixel first, bottom-right pixel last. Y10 is presented as YUV 4:4:4 on the AXI4-Stream interface.

Table 8: Y10 Format

9:0	9 19:10 29:20		31:30
YO	Y1	Y2	Х

AXI4-Lite Control Interface

The AXI4-Lite interface allows you to dynamically control the parameters within the core. The configuration can be accomplished by using an AXI4-Lite master state machine, an embedded Arm[®] processor, or a soft system processor such as MicroBlaze[™] processor. The Video Scene Change Detection IP can be controlled through the AXI4-Lite interface by using functions provided by the driver in the Vitis[™] software platform. Another method is by performing read and write transactions to the register space, but this method is only used when the first method is not available. The following table shows the AXI4-Lite control interface signals. This interface runs at the ap_clk clock.



Table 9: AXI4-Lite Control Interface Signals

Signal Name	I/O	Width	Description
s_axi_ctrl_aresetn	Ι	1	Reset
s_axi_ctrl_aclk	Ι	1	Clock
s_axi_ctrl_awaddr	I	18	Write Address
s_axi_ctrl_awprot	Ι	3	Write Address Protection
s_axi_ctrl_awvalid	Ι	1	Write Address Valid
s_axi_ctrl_awready	0	1	Write Address Ready
s_axi_ctrl_wdata	Ι	32	Write Data
s_axi_ctrl_wstrb	Ι	4	Write Data Strobe
s_axi_ctrl_wvalid	Ι	1	Write Data Valid
s_axi_ctrl_wready	0	1	Write Data Ready
s_axi_ctrl_bresp	0	2	Write Response
s_axi_ctrl_bvalid	0	1	Write Response Valid
s_axi_ctrl_bready	Ι	1	Write Response Ready
s_axi_ctrl_araddr	Ι	18	Read Address
s_axi_ctrl_arprot	Ι	3	Read Address Protection
s_axi_ctrl_arvalid	Ι	1	Read Address Valid
s_axi_ctrl_aready	0	1	Read Address Ready
s_axi_ctrl_rdata	0	32	Read Data
s_axi_ctrl_rresp	0	2	Read Data Response
s_axi_ctrl_rvalid	0	1	Read Data Valid
s_axi_ctrl_rready	Ι	1	Read Data Ready

Register Space

The Video Scene Change Detection IP has specific registers which allow you to control the operation of the core. All registers have an initial value of zero. The following table provides a detailed description of all the registers that apply globally to the IP.





Table 10: Register Address Space

Address (hex) BASEADDR+	Register Name	Access Type	Register Description
0x0000	Control	R/W	Bit[0] = ap_start Bit[1] = ap_done Bit[2] = ap_idle Bit[3] = ap_ready Bit[5] = Flush pending AXI transactions Bit[6] = Flush done Bit[7] = auto_restart Others = Reserved
0x0004	Global Interrupt Enable	R/W	Bit[0] = Global interrupt enable Others = Reserved
0x0008	IP Interrupt Enable	R/W	Bit[0] = Channel 0 (ap_done) Bit[1] = Channel 1 (ap_ready) Others = Reserved
0x000C	IP Interrupt Status Register	R/TOW (1)	Bit[0] = Channel 0 (ap_done) Bit[1] = Channel 1 (ap_ready) Others = Reserved
0x00010	HwReg_width_0	R/W	Bit[15] to Bit[0] = HwReg_width_0[15:0] Others = Reserved
0x0018	HwReg_height_0	R/W	Bit[15] to Bit[0] = HwReg_height_0[15:0] Others = Reserved
0x0020	HwReg_stride_0	R/W	Bit[15] to Bit[0] = HwReg_stride_0[15:0] Others = Reserved
0x0028	HwReg_video_format_0	R/W	Bit[15] to Bit[0] = HwReg_video_format_0[15:0] Others = Reserved
0x0030	HwReg_subsample_0	R/W	Bit[15] to Bit[0] = HwReg_subsample_0[15:0] Others = Reserved
0x0038	HwReg_sad0	R	Bit[31] to Bit[0] = HwReg_sad0[31:0] Others = Reserved
0x0040	HwReg_frm_buffer0_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer0_V[31:0] Others = Reserved



Address (hex) BASEADDR+	Register Name	Access Type	Register Description
0x00110	HwReg_width_1	R/W	Bit[15] to Bit[0] = HwReg_width_1[15:0] Others = Reserved
0x00118	HwReg_height_1	R/W	Bit[15] to Bit[0] = HwReg_height_1[15:0] Others = Reserved
0x00120	HwReg_stride_1	R/W	Bit[15] to Bit[0] = HwReg_stride_1[15:0] Others = Reserved
0x00128	HwReg_video_format_1	R/W	Bit[15] to Bit[0] = HwReg_video_format_1[15:0] Others = Reserved
0x00130	HwReg_subsample_1	R/W	Bit[15] to Bit[0] = HwReg_subsample_1[15:0] Others = Reserved
0x00138	HwReg_sad1	R	Bit[31] to Bit[0] = HwReg_sad1[31:0] Others = Reserved
0x00140	HwReg_frm_buffer1_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer1_V[31:0] Others = Reserved
0x00210	HwReg_width_2	R/W	Bit[15] to Bit[0] = HwReg_width_2[15:0] Others = Reserved
0x00218	HwReg_height_2	R/W	Bit[15] to Bit[0] = HwReg_height_2[15:0] Others = Reserved
0x00220	HwReg_stride_2	R/W	Bit[15] to Bit[0] = HwReg_stride_2[15:0] Others = Reserved
0x00228	HwReg_video_format_2	R/W	Bit[15] to Bit[0] = HwReg_video_format_2[15:0] Others = Reserved
0x00230	HwReg_subsample_2	R/W	Bit[15] to Bit[0] = HwReg_subsample_2[15:0] Others = Reserved
0x00238	HwReg_sad2	R	Bit[31] to Bit[0] = HwReg_sad2[31:0] Others = Reserved



Address (hex) BASEADDR+	Register Name	Access Type	Register Description
0x00240	HwReg_frm_buffer2_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer2_V[31:0] Others = Reserved
0x00310	HwReg_width_3	R/W	Bit[15] to Bit[0] = HwReg_width_3[15:0] Others - Reserved
0x00318	HwReg_height_3	R/W	Bit[15] to Bit[0] = HwReg_height_3[15:0] Others = Reserved
0x00320	HwReg_stride_3	R/W	Bit[15] to Bit[0] = HwReg_stride_3[15:0] Others = Reserved
0x00328	HwReg_video_format_3	R/W	Bit[15] to Bit[0] = HwReg_video_format_3[15:0] Others = Reserved
0x00330	HwReg_subsample_3	R/W	Bit[15] to Bit[0] = HwReg_subsample_3[15:0] Others = Reserved
0x00338	HwReg_sad3	R	Bit[31] to Bit[0] = HwReg_sad3[31:0] Others = Reserved
0x00340	HwReg_frm_buffer3_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer3_V[31:0] Others = Reserved
0x00410	HwReg_width_4	R/W	Bit[15] to Bit[0] = HwReg_width_4[15:0] Others - Reserved
0x00418	HwReg_height_4	R/W	Bit[15] to Bit[0] = HwReg_height_4[15:0] Others = Reserved
0x00420	HwReg_stride_4	R/W	Bit[15] to Bit[0] = HwReg_stride_4[15:0] Others = Reserved
0x00428	HwReg_video_format_4	R/W	Bit[15] to Bit[0] = HwReg_video_format_4[15:0] Others = Reserved
0x00430	HwReg_subsample_4	R/W	Bit[15] to Bit[0] = HwReg_subsample_4[15:0] Others = Reserved



Address (hex) BASEADDR+	Register Name	Access Type	Register Description
0x00438	HwReg_sad4	R	Bit[31] to Bit[0] = HwReg_sad4[31:0] Others = Reserved
0x00440	HwReg_frm_buffer4_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer4_V[31:0] Others = Reserved
0x00510	HwReg_width_5	R/W	Bit[15] to Bit[0] = HwReg_width_5[15:0] Others - Reserved
0x00518	HwReg_height_5	R/W	Bit[15] to Bit[0] = HwReg_height_5[15:0] Others = Reserved
0x00520	HwReg_stride_5	R/W	Bit[15] to Bit[0] = HwReg_stride_5[15:0] Others = Reserved
0x00528	HwReg_video_format_5	R/W	Bit[15] to Bit[0] = HwReg_video_format_5[15:0] Others = Reserved
0x00530	HwReg_subsample_5	R/W	Bit[15] to Bit[0] = HwReg_subsample_5[15:0] Others = Reserved
0x00538	HwReg_sad5	R	Bit[31] to Bit[0] = HwReg_sad5[31:0] Others = Reserved
0x00540	HwReg_frm_buffer5_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer5_V[31:0] Others = Reserved
0x00610	HwReg_width_6	R/W	Bit[15] to Bit[0] = HwReg_width_6[15:0] Others - Reserved
0x00618	HwReg_height_6	R/W	Bit[15] to Bit[0] = HwReg_height_6[15:0] Others = Reserved
0x00620	HwReg_stride_6	R/W	Bit[15] to Bit[0] = HwReg_stride_6[15:0] Others = Reserved
0x00628	HwReg_video_format_6	R/W	Bit[15] to Bit[0] = HwReg_video_format_6[15:0] Others = Reserved



Address (hex) BASEADDR+	Register Name	Access Type	Register Description
0x00630	HwReg_subsample_6	R/W	Bit[15] to Bit[0] = HwReg_subsample_6[15:0] Others = Reserved
0x00638	HwReg_sad6	R	Bit[31] to Bit[0] = HwReg_sad6[31:0] Others = Reserved
0x00640	HwReg_frm_buffer6_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer6_V[31:0] Others = Reserved
0x00710	HwReg_width_7	R/W	Bit[15] to Bit[0] = HwReg_width_7[15:0] Others - Reserved
0x00718	HwReg_height_7	R/W	Bit[15] to Bit[0] = HwReg_height_7[15:0] Others = Reserved
0x00720	HwReg_stride_7	R/W	Bit[15] to Bit[0] = HwReg_stride_7[15:0] Others = Reserved
0x00728	HwReg_video_format_7	R/W	Bit[15] to Bit[0] = HwReg_video_format_7[15:0] Others = Reserved
0x00730	HwReg_subsample_7	R/W	Bit[15] to Bit[0] = HwReg_subsample_7[15:0] Others = Reserved
0x00738	HwReg_sad7	R	Bit[31] to Bit[0] = HwReg_sad7[31:0] Others = Reserved
0x00740	HwReg_frm_buffer7_V	R/W	Bit[31] to Bit[0] = HwReg_frm_buffer7_V[31:0] Others = Reserved
0x00780	HwReg_stream_enable	R/W	Bit[15] to Bit[0] = HwReg_stream_enable[15:0] Others = Reserved

Notes:

1. SC = Self Clear, COR = Clear on Read, TOW = Toggle on Write, COH = Clear on Handshake.



Control (0x0000) Register

This register controls the operation of the video scene change detection. Bit[0] of the control register, ap_start, kicks off the core from the software. Writing 1 to this bit, starts the core to generate a video frame. To set the core in free running mode, Bit[7] of this register, auto_restart, must be set to 1. Bits[3:1] are reserved for future use.

Bit[5] is for flushing pending AXI transactions. This bit should be set and held (until reset) by the software to flush pending transactions. When this is set, the hardware is expecting a hard reset. Bit[6] is the flush status bit and is asserted when the flush is done. Bit[5] and Bit[6] are valid only when the IP is running in the memory mode.

Global Interrupt Enable (0x0004) Register

This register is the master control for all interrupts. Bit[0] can be used to enable/disable all core interrupts.

IP Interrupt Enable (0x0008) Register

This register allows interrupts to be enabled selectively. Currently, two interrupt sources are available; ap_done and ap_ready. ap_done is triggered after the frame processing is complete, while ap_ready is triggered after the core is ready to start processing the next frame.

IP Interrupt Status (0x000C) Register

This is a dual purpose register. When an interrupt occurs, the corresponding interrupt source bit is set in this register. In readback mode (Get status), the interrupting source can be determined. In writeback mode (Clear interrupt), the requested interrupt source bit is cleared.

IP HwReg_Width_0 (0x0010) Register

This register allows you to program the width of the first input color image in a batch of up to eight streams for memory based mode. This register is also applicable for the stream based mode which supports only one stream. Supported values are between 64 and the value provided in the Maximum Number of Columns field in the Vivado[®] Integrated Design Environment (IDE). To avoid processing errors, you should restrict the values written to this register to the range supported by the core instance.





IP HwReg_Height_0 (0x0018) Register

This register allows you to program the height of the first input color image in a batch of up to maximum 8 streams for memory based mode. This register is also applicable for the stream based mode which supports only one stream. Supported values are between 64 and the value provided in the Maximum Number of Rows field in the Vivado Integrated Design Environment (IDE). To avoid processing errors, you should restrict the values written to this register to the range supported by the core instance.

IP HwReg_stride_0 (0x0020) Register

This register allows you to program the stride required for the height of the first input color image in a batch of up to 8 streams for memory based mode. This register is not applicable for IP stream based mode operation.

IP HwReg_video_format_0 (0x0028) Register

This register allows to program the pixel format of the first input image which is to be read from the source buffer. For memory based mode, use 24 for Y8 or 25 for Y10. For stream based mode, use 0 for RGB, 1 for YUV444, 2 for YUV422, and 3 for YUV420.

IP HwReg_subsample_0 (0x0030) Register

This register allows you to program the vertical subsampling factor of the first input color image in a batch of up to eight streams for memory based mode. This is also applicable for single stream in the stream based mode. Instead of sampling every line to calculate the histogram, the IP uses this register value to sample only specific lines of the frame. Valid values are 2, 4, 8, 16, 32, or 64. Typical value to be used is 16. To avoid processing errors, you should restrict the values written to this register to the range supported by the core instance.

IP HwReg_sad0 (0x0038) Register

This is a read only register that returns the value of the SAD between current and previous histogram of the first input color image in a batch of up to eight streams for memory based mode. This register is also applicable for the stream based mode.

The final scene change determination is made as shown in the following equation. While the threshold is programmable, a good default value to start with is 0.5.

 $\frac{\text{SAD}}{\frac{\text{width*height}}{\text{subsample factor}}} > \text{threshold}$



IP HwReg_frm_buffer0_V (0x0040) Register

In the memory based mode, this register specifies the frame buffer address that holds the luma pixel data for the first stream. The address needs to be aligned to the data size of the memory mapped AXI4 interface. For the Video Scene Change Detection IP, the data size of the memory mapped AXI4 interface is 32. This register is not applicable when the IP is working in the stream mode.

If the IP is configured to a 64 bit address width in the IP GUI, the IP internally creates another register in the register space by adding 0x4 to the existing buffer address register offset. For example, HwReg_frm_buffer0_V register addresses are 0x0040 and 0x0044. Register addresses for all outputs are also calculated in a similar way.

IP HwReg_stream_enable (0x00780) Register

This register need to be programmed as per the streams executed as part of a batch for memory based mode. Bit 0 is for stream 1, bit 1 is for stream 2, likewise bit 7 is for stream 8. This register is not applicable for stream base mode operation of the IP as there is only one stream.

IMPORTANT! The registers related to the first input stream are described above, the same description is applicable for the remaining seven input streams for memory based mode of operation. See Register Address Space table for the address offsets of the registers related to the remaining seven output streams. The registers ending with _0 are also mentioned in the register address space table. These registers are also applicable for stream mode.

Accessing 64-bit DDR Memory Location

Perform the following steps to access the 64-bit DDR memory location:

- 1. Change the IP address width to 64-bit in the IP GUI.
- 2. In the Vivado[®] address editor, unmap the HPO_DDR_LOW base name which has 0x0000_0000 offset address with 2G band.
- 3. Auto assign addresses to map DDR_LOW and DDR_HIGH address spaces for 64-bit mode.
- 4. Vivado Design Suit will get DDR_HIGH offset address as 0x0000_0008_0000_0000 with 32G band. The IP can use any address as source/destination buffer address.



Chapter 4

Designing with the Core

This section includes guidelines and additional information to facilitate designing with the core.

General Design Guidelines

Use the Example Design

Each instance of the Video Scene Change Detection core created by the Vivado design tool is delivered with an example design that can be implemented in a device and then simulated. This design can be used as a starting point for your own design or can be used to sanity-check your application in the event of difficulty. See the Example Design content for information about using and customizing the example designs for the core.

Registering Signals

To simplify timing and increase system performance in a programmable device design, keep all inputs and outputs registered between the user application and the core. This means that all inputs and outputs from the user application should come from, or connect to, a flip-flop. While registering signals might not be possible for all paths, it simplifies timing analysis and makes it easier for the Xilinx[®] tools to place and route the design.

Recognize Timing Critical Signals

The constraints provided with the example design identify the critical signals and timing constraints that should be applied.

Make Only Allowed Modifications

You should not modify the core. Any modifications can have adverse effects on system timing and protocol compliance. Supported user configurations of the core can only be made by selecting the options in the customization IP dialog box when the core is generated.





Clocking

The Video Scene Change Detection IP has only one clock domain. All interfaces in the IP such as, AXI4-Lite, memory mapped AXI4, and AXI4-Stream interfaces use the ap_clk pin as a clock source.

Resets

The Video Scene Change Detection IP has ap_rst_n pin as a hardware reset option. No software reset option is available. The external reset pulse needs to be held for 16 or more ap_clk cycles to reset the core. The ap_rst_n signal is synchronous to the ap_clk clock domain. The ap_rst_n signal resets the entire core including the AXI4-Lite, memory mapped AXI4, and AXI4-Stream interfaces.

Programming Sequence

The buffer parameters of the IP can be changed dynamically and the change is picked up immediately. If you want to change the width, height, stride, or video format, or if you want to restart the entire system, it is recommended that the pipelined Xilinx IP video cores are disabled/ reset from the system output to input, and programmed/enabled from the system output to input.

In memory based mode, the pending AXI transactions can be flushed before reseting the IP. Assert and hold Bit[5] of the control register. Bit[6] asserts when the flush is complete and then the IP can be reset. In memory based operations, the IP works as follows. Up to eight (this is configurable and programmable) frames can be processed in one batch through the scene change detection algorithm; the following is the driver programming sequence:

- 1. Program the registers as per the number of streams to be processed in a batch.
- 2. Program the required registers per stream (width, height, stride, format, subsampling factor, buffer pointer).
- 3. Subscribe to the ap_done interrupt.
- 4. Write ap_start to the control register (note do not enable auto restart), which will then kick off the hardware.
- 5. On ap_done interrupt (only 1 per batch), read each SAD value per stream from the appropriate register.
- 6. Make the final scene change decision per stream (thresholding).



7. Go back to step 1.

In stream based operation, the following is the driver programming sequence:

- 1. Program the required registers per stream (width, height, stride, format, subsampling factor).
- 2. Subscribe to the ap_done interrupt.
- 3. Write ap_start to the control register (note do not enable auto restart), which will then kick off the hardware.
- 4. On ap_done interrupt, read sad0 register value.
- 5. Make the final scene change decision (thresholding).
- 6. Go back to step 1.





Chapter 5

Design Flow Steps

This section describes customizing and generating the core, constraining the core, and the simulation, synthesis, and implementation steps that are specific to this IP core. More detailed information about the standard Vivado[®] design flows and the IP integrator can be found in the following Vivado Design Suite user guides:

- Vivado Design Suite User Guide: Designing IP Subsystems using IP Integrator (UG994)
- Vivado Design Suite User Guide: Designing with IP (UG896)
- Vivado Design Suite User Guide: Getting Started (UG910)
- Vivado Design Suite User Guide: Logic Simulation (UG900)

Customizing and Generating the Core

This section includes information about using Xilinx[®] tools to customize and generate the core in the Vivado[®] Design Suite.

If you are customizing and generating the core in the Vivado IP integrator, see the Vivado Design Suite User Guide: Designing IP Subsystems using IP Integrator (UG994) for detailed information. IP integrator might auto-compute certain configuration values when validating or generating the design. To check whether the values do change, see the description of the parameter in this chapter. To view the parameter value, run the validate_bd_design command in the Tcl console.

You can customize the IP for use in your design by specifying values for the various parameters associated with the IP core using the following steps:

- 1. Select the IP from the IP catalog.
- 2. Double-click the selected IP or select the Customize IP command from the toolbar or rightclick menu.

For details, see the Vivado Design Suite User Guide: Designing with IP (UG896) and the Vivado Design Suite User Guide: Getting Started (UG910).

Figures in this chapter are illustrations of the Vivado IDE. The layout depicted here might vary from the current version.



User Parameters

The following table shows the relationship between the fields in the Vivado[®] IDE and the user parameters (which can be viewed in the Tcl Console).

Table 12: User Parameters

Vivado IDE Parameter/Value ¹	User Parameter/Value	Default Value
Memory Based	MEMORY_BASED	1
Samples per Clock	SAMPLES_PER_CLOCK	2
Maximum Data Width	MAX_DATA_WIDTH	8
Maximum number of Columns	MAX_COLS	8192
Maximum number of Rows	MAX_ROWS	4320
AXIMM Data Width	AXIMM_DATA_WIDTH	32
AXIMM Address Width	AXIMM_ADDR_WIDTH	32
Number Read Outstanding	AXIMM_NUM_OUTSTANDING	4
Transaction Burst Length	AXIMM_BURST_LENGTH	16
Number of Histogram Bins	HISTOGRAM_BITS	64
Maximum Number of Streams	MAX_NR_STREAMS	1
Y8	HAS_Y8	1
Y10	HAS_Y10	0

Notes:

1. Parameter values are listed in the table where the Vivado IDE parameter value differs from the user parameter value. Such values are shown in this table as indented below the associated parameter.

Output Generation

For details, see the Vivado Design Suite User Guide: Designing with IP (UG896).

Interface

The Video Scene Change Detection IP is configured to meet your specific needs through the Vivado Design Suite. This section provides a quick reference to the parameters that can be configured at generation time.

The following figure shows the Video Scene Change Detection Vivado IDE Configuration screen.



Figure 3: Video Scene Change Detection Customize IP Screen (Memory based mode)

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	Maximum Number of Rows 2160 (64 - 4320)	
	Number of Histogram Bins 64 🗸	
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	Address Width 32 🗸	
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	✓ Y8 □ Y10	
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Figure 4: Video Scene Change Detection Customize IP Screen (Stream based mode)

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	Maximum Number of Rows	2160 💿	[64 - 4320]	
	Maximum Data Width	8 ~		
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• ap_rst_n				

General Settings

The following are the applicable general settings:

- **Component Name:** The component name is used as the base name of output files generated for the module. Names must begin with a letter and must be composed from characters: a to z, 0 to 9, and "_".
- Samples Per Clock: Specifies the number of pixels processed per clock cycle. Permitted values are one, two, and four samples per clock. This parameter determines the IP throughput. Throughput is proportional to the number of samples per clock. Larger throughput requires more number of hardware resources.

Note: This property applies to all the outputs of the Video Scene Change Detection IP.

- Maximum Data Width: Specifies the bit width of input and output samples on all the interfaces. Permitted values are 8, 10, 12, and 16 bits for stream based mode. This parameter is not applicable when the memory based mode is enabled.
- Maximum Number of Columns: Specifies maximum active video columns/pixels the IP core could produce at run-time. Any video width that is less than the maximum number of columns can be programmed through AXI4-Lite control interface without regenerating the core.



- **Maximum Number of Rows:** Specifies maximum active video rows/lines the IP core could produce at run-time. Any video height that is less than maximum number of rows can be programmed through the AXI4-Lite control interface without regenerating the core.
- Number of Histogram Bins: Specifies the number of bins used to calculate the histogram. Number of bits used to store the luma values is proportional to the selected value. The recommended value is 64.
- Maximum Number of Streams: Applicable only when the memory based mode is selected. Specifies the number of memory streams for which we want to detect the scene change. The permitted values are 1, 2, 3, 4, 5, 6, 7, or 8.
- Address Width: Specifies the AXI MM address width. This is applicable only for the memory based mode. The permitted values are 32 and 64.
- Y8 Pixel Format: Applicable for memory based mode only.
- Y10 Pixel Format: Applicable for memory based mode only.

Constraining the Core/Subsystem

Required Constraints

This section is not applicable for this IP core.

Device, Package, and Speed Grade Selections

This section is not applicable for this IP core.

Clock Frequencies

This section is not applicable for this IP core.

Clock Management

This section is not applicable for this IP core.

Clock Placement

This section is not applicable for this IP core.

Banking

This section is not applicable for this IP core.





Transceiver Placement

This section is not applicable for this IP core.

I/O Standard and Placement

This section is not applicable for this IP core.

Simulation

For comprehensive information about Vivado[®] simulation components, as well as information about using supported third-party tools, see the *Vivado Design Suite User Guide: Logic Simulation* (UG900).

Simulation of this core is not supported.

Synthesis and Implementation

For details about synthesis and implementation, see the Vivado Design Suite User Guide: Designing with IP (UG896).





Chapter 6

Example Design

This chapter provides an example design, including the description of important system-level aspects, when designing with the Video Scene Change Detection IP such as:

- Video Scene Change Detection usage with memory mapped AXI4 interface memory buffers.
- Typical usage of the Video Scene Change Detection IP in conjunction with other cores.
- Configuration of the Video Scene Change Detection IP by programming the registers.

Note: The example design is only available on the Xilinx[®] ZCU106 evaluation board.

The Video Scene Change Detection IP calculates the sum of absolute differences (SAD) between consecutive video frames received on either memory or stream interface. You can select the desired interface from the GUI. First the IP driver receives the SAD values, then the IP compares these values with the threshold values and notifies you about the scene change. Following are the two types of example design flows:

- Memory based mode example design flow: The Video Scene Change Detection IP supports eight streams in the memory mode. You need to configure the number of streams, height, width, stride, buffer address, threshold value for SAD, and subsample value in the registers. The final scene change determination happens based on the threshold value specified by you. The example application then writes different patterns in the buffer address for scene change detection. The video scene change driver notifies the SAD values with the stream number in which the scene change has happened with the help of callback functions.
- Stream based mode example design flow: The Video Scene Change Detection IP supports only one stream in the stream mode. You need to configure the height, width, stride, buffer address, threshold value for SAD, and subsample value in the registers. The final scene change determination happens based on the threshold value specified by you. The example application generates different TPG patterns using TPG and observes the video scene change based on the given threshold value.

The supported platforms are listed in the following table:

Table 13: Supported Platforms

Development Boards	Additional Hardware	Processor
ZCU106	N/A	A53

Perform the following steps to open the example project:



- 1. Select the Video Scene Change Detection IP from the Vivado[®] IP catalog.
- 2. Double-click the selected IP or right-click the IP and select **Customize IP** from the menu.
- 3. Configure the build-time parameters in the **Customize IP** window and click **OK**. The Vivado IDE generates an example design matching the build-time configuration.
- 4. In the **Generate Output Products** window, select **Generate** or **Skip**. If **Generate** is selected, the IP output products are generated after a brief moment.
- 5. Right-click Video Scene Change Detection in Sources panel and select Open IP Example Design from the menu.
- 6. In the **Open IP Example Design** window, select example project directory and click **OK**. The Vivado software then runs automation to generate the example design in the selected directory.

The generated project contains a synthesizable example design. The following figure shows the **Source** panel of the example project. Synthesizable example block design, along with top-level file, resides in **Design Sources** catalog.



Figure 6: Video Scene Change Detection Project Source Panel





Synthesizable Example Design

The synthesizable design uses Zynq[®] UltraScale+[™] MPSoC processor, AXI4 master, and PS DDR controller core to access DDR memory. The interrupt port of the Video Scene Change Detection IP is connected to Zynq UltraScale+ MPSoC. The IP sends interrupt signals after generating the SAD values for all input streams in memory based mode.



Figure 7: **Synthesizable Example Block Design**

The synthesizable example design requires both Vivado and Vitis[™] tools.

The first step is to run synthesis, implementation, and bitstream generation in Vivado tools. After completing these steps, select **File** > **Export** > **Export Hardware**.

In the window, select Include bitstream, then select an export directory and click OK.

The remaining work is performed in the Xilinx Vitis tool. The Video Scene Change Detection IP example design application file can be found in the following Vitis directory: /data/ embeddedsw/XilinxProcessorIPLib/drivers/v_scenechange/examples/

The example application design source files in the examples folder are tightly coupled with the $v_scenechange$ example design available in the Vivado IP catalog. Perform the following steps to generate the executable application for the example design:

1. Open the Vitis software platform



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3. Add the .xsa file created using Vivado.





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6. In the New Application Project window, select the appropriate CPU, OS, and Language to generate the application (in C language), as shown in the following figure :



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8. To create/run the design-related application elf file. Open the Explorer window in the Vitis software platform and select project name and the appropriate application, as shown in the following figure:

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9. Select the target application and click **OK**. The following window appears:

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10. Upon selecting the application source files, the Vitis software platform compiles the application and generates an elf file in the Debug folder in the Explorer window.

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Note:

- Select the relevant application for memory or stream mode to build the application, it generates the elf file.
- Use XSDB tools to download the bit stream and the elf files on the ZCU106 board.

The example application may require modifications based on the configuration made in the IP customization GUI.



Chapter 7

Test Bench

There is no test bench for this IP core release.





Appendix A

Verification, Compliance, and Interoperability

Simulation

A highly parameterizable test bench was used to test the Video scene change detection in Vivado[®] High-Level Synthesis (HLS). Testing included the following:

- Register accesses
- Processing multiple frames of data
- Varying IP throughput and pixel data width
- Testing the Video Scene Change Detection IP with memory mapped AXI4 interface or AXI4-Stream interface
- Testing of various frame sizes
- Varying parameter settings
- Testing Video Scene Change Detection for multiple input streams in memory base mode

Hardware Testing

The Video Scene Change Detection core has been validated at Xilinx[®] to represent many different parameterizations. A test design was developed for the core that incorporated a Zynq UltraScale+ MPSoC processor, AXI4-Lite interconnect, and various other peripherals. The MPSoC processor is responsible for:

- Programing the video scene change detection IP registers
- Launching the test
- Reporting the Pass/Fail status of the test and any errors that were found

Interoperability

The core slave (input) and master (output) AXI4-Stream interface can work directly with any core that produces RGB, YUV 4:4:4, YUV 4:2:2, or YUV 4:2:0 video data.



Appendix B

Upgrading

This appendix is not applicable for the first release of the core.





Appendix C

Application Software Development

The Video Scene Change Detection IP core is delivered with a bare-metal driver as part of the Vitis[™] software platform installation. The driver follows a layered architecture wherein layer 1 provides basic register peek/poke capabilities and requires you to be familiar with the register map and inner workings of the core. Layer 2, on the other hand, abstracts away all the lower level details and provides an easy to use functional interface to the Video Scene Change Detection IP. Xilinx[®] recommends always using layer 2 APIs to interact with the core.

Building the BSP

When the Board Support Package (BSP) is built, the Video scene change driver inherently pulls in the required dependency drivers if any. During the build process the Video scene change driver extracts the Video scene change detection hardware configuration settings from the provided hardware design file.

Modes of Operation

The Video Scene Change DetectionIP supports two modes of operation, which require two different programming models.

- Auto Restart Mode (Default): The driver initialization routine configures the Video Scene Change Detection for auto restart mode. In this mode, after the current frame is processed the core automatically triggers the start of the next frame processing. Consequently, the core can keep on processing frames without any software intervention, with settings applied when the core was started. You can switch to Auto Restart Mode, at any time, by disabling the interrupts, using the XV_scenechange_InterruptDisable API.
- Interrupt Mode: In this mode, the interrupt (IRQ) port of the core needs to be connected to a system interrupt controller. When an interrupt is triggered, the core interrupt service routine (ISR) checks to confirm if current frame processing is complete. It then calls a user programmable callback function, if any. In the callback function, the register settings for the next frame should be programmed, that is, what source memory buffer address a frame should read next from. Finally, the interrupt service routine triggers the core to start processing the next frame.



An application must perform the following tasks to configure the core for Interrupt mode.

- Register the core ISR routine XV_scenechange_InterruptHandler with the system interrupt controller.
- Register the application callback function that should be called within the interrupt context. This can be done using the API XV_scenechange_SetCallback.
- Enable the interrupts by calling provided API $\tt XV_scenechange_InterruptEnable.$

Usage

To better understand the driver usage, consider the following test case scenario. Suppose the core in the design was configured with memory based mode and eight input strems. Driver should program the input image width, input image height, stride for input image, video format of the input image, sampling rate, and source buffer address registers for all the configured eight input streams. The application should allocate required frame buffer space for each input stream in memory. These addresses can be updated during the interrupt. To integrate and use the Video Scene Change driver in the application, the following steps should be performed:

- 1. Include the driver header file xv_scenechange.h that contains the Video Scene Change Detection IP instance object definition.
- 2. Declare an instance of the Video Scene Change Detection IP type: XV_scenechange ScdPtr;.
- 3. Initialize the Video Scene Change DetectionIP instance at power on: XV_scenechange_Initialize(&ScdPtr, DeviceId);. This function accesses the hardware configuration and initializes the core instance structure.
- 4. If the core is operating in an interrupt mode, the application needs to perform the tasks mentioned, that is, register the ISR with the system interrupt controller and set the application callback function. This function is called by the Video Scene Change Detection IP driver when the frame done IRQ is triggered.
- 5. If applicable, write the application level callback function. An example action to be performed here would be to update Source Image buffer addresses i.e. from where to read the next frame data for each output. This allows the application to render the frame updates in memory, on screen.
- 6. Set the number of input streams for memory based mode by the function XV_scenechange_Set_HwReg_stream_enable(&ScdPtr, ScdPtr.userval_stream);.
- 7. Configure input image width, input image height, input image width, stride for input image, video format of the input image, subsampling rate, and source buffer address registers for all the configured streams.



- 8. Enable the interrupts using the following functions:
 - XV_scenechange_InterruptGlobalEnable(&ScdPtr);
 - XV_scenechange_InterruptEnable(&ScdPtr, XV_SCENECHANGE_CTRL_ADDR_ISR_AP_DONE).
- 9. Start the IP using the XV_scenechange_Start(&ScdPtr) function and wait for the interrupt.

Note:

- 1. Resolution changes are not possible on the fly. If the changes are needed then the application must reset the Video Scene Change Detection, that is toggle ap_rst_n, and reconfigure the core for the new resolution. After reset, all registers are cleared to 0.
- 2. The application code should check the return status of all APIs to make sure the required action was completed successfully and if not take corrective action.





Appendix D

Debugging

This appendix includes details about resources available on the Xilinx[®] Support website and debugging tools.

Finding Help on Xilinx.com

To help in the design and debug process when using the core, the Xilinx Support web page contains key resources such as product documentation, release notes, answer records, information about known issues, and links for obtaining further product support. The Xilinx Community Forums are also available where members can learn, participate, share, and ask questions about Xilinx solutions.

Documentation

This product guide is the main document associated with the core. This guide, along with documentation related to all products that aid in the design process, can be found on the Xilinx Support web page or by using the Xilinx® Documentation Navigator. Download the Xilinx Documentation Navigator from the Downloads page. For more information about this tool and the features available, open the online help after installation.

Answer Records

Answer Records include information about commonly encountered problems, helpful information on how to resolve these problems, and any known issues with a Xilinx product. Answer Records are created and maintained daily ensuring that users have access to the most accurate information available.

Answer Records for this core can be located by using the Search Support box on the main Xilinx support web page. To maximize your search results, use keywords such as:

- Product name
- Tool message(s)
- Summary of the issue encountered



A filter search is available after results are returned to further target the results.

Master Answer Record for the Video Scene Change Detection

AR 70293.

Technical Support

Xilinx provides technical support on the Xilinx Community Forums for this LogiCORE[™] IP product when used as described in the product documentation. Xilinx cannot guarantee timing, functionality, or support if you do any of the following:

- Implement the solution in devices that are not defined in the documentation.
- Customize the solution beyond that allowed in the product documentation.
- Change any section of the design labeled DO NOT MODIFY.

To ask questions, navigate to the Xilinx Community Forums.

Debug Tools

There are many tools available to address Video Scene Change Detection design issues. It is important to know which tools are useful for debugging various situations.

Vivado Design Suite Debug Feature

The Vivado[®] Design Suite debug feature inserts logic analyzer and virtual I/O cores directly into your design. The debug feature also allows you to set trigger conditions to capture application and integrated block port signals in hardware. Captured signals can then be analyzed. This feature in the Vivado IDE is used for logic debugging and validation of a design running in Xilinx[®] devices.

The Vivado logic analyzer is used to interact with the logic debug LogiCORE IP cores, including:

- ILA 2.0 (and later versions)
- VIO 2.0 (and later versions)

See the Vivado Design Suite User Guide: Programming and Debugging (UG908).





Hardware Debug

Hardware issues can range from link bring-up to problems seen after hours of testing. This section provides debug steps for common issues. The Vivado[®] debug feature is a valuable resource to use in hardware debug. The signal names mentioned in the following individual sections can be probed using the debug feature for debugging the specific problems.

General Checks

Ensure that all the timing constraints for the core were properly incorporated from the example design and that all constraints were met during implementation.

- Does it work in post-place and route timing simulation? If problems are seen in hardware but not in timing simulation, this could indicate a PCB issue. Ensure that all clock sources are active and clean.
- If using MMCMs in the design, ensure that all MMCMs have obtained lock by monitoring the locked port.
- If your outputs go to 0, check your licensing.





Appendix E

Additional Resources and Legal Notices

Xilinx Resources

For support resources such as Answers, Documentation, Downloads, and Forums, see Xilinx Support.

Documentation Navigator and Design Hubs

Xilinx[®] Documentation Navigator (DocNav) provides access to Xilinx documents, videos, and support resources, which you can filter and search to find information. To open DocNav:

- From the Vivado[®] IDE, select Help → Documentation and Tutorials.
- On Windows, select Start → All Programs → Xilinx Design Tools → DocNav.
- At the Linux command prompt, enter docnav.

Xilinx Design Hubs provide links to documentation organized by design tasks and other topics, which you can use to learn key concepts and address frequently asked questions. To access the Design Hubs:

- In DocNav, click the **Design Hubs View** tab.
- On the Xilinx website, see the Design Hubs page.

Note: For more information on DocNav, see the Documentation Navigator page on the Xilinx website.

References

These documents provide supplemental material useful with this guide:



- 1. Vivado Design Suite: AXI Reference Guide (UG1037)
- 2. Vivado Design Suite User Guide: Designing IP Subsystems using IP Integrator (UG994)
- 3. Vivado Design Suite User Guide: Designing with IP (UG896)
- 4. Vivado Design Suite User Guide: Getting Started (UG910)
- 5. Vivado Design Suite User Guide: Logic Simulation (UG900)
- 6. ISE to Vivado Design Suite Migration Guide (UG911)
- 7. Vivado Design Suite User Guide: Programming and Debugging (UG908)
- 8. Vivado Design Suite User Guide: Implementation (UG904)
- 9. Video Processing Subsystem Reference Design (XAPP1291)

Revision History

The following table shows the revision history for this document.

Section	Revision Summary			
12/09/2019 Version 1.0				
Synthesizable Example Design	 Updated SDK instances to Vitis software platform. Updated Example Design Software section with the Vitis software platform flow. 			
06/18/2019	Version 1.0			
Features	Updated.			
Accessing 64-bit DDR Memory Location	Added new section.			
12/05/2018 Version 1.0				
Initial release.	N/A			

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